

Homework #8 Solutions

- 1 -

ECE 603

Fall, 2016

1) (a) $P_x = R_x(0) = 1$

(b) Yes. WSS & Gaussian \Rightarrow SSS

(c) Let $R = X(3)$. Because $X(t)$ is a Gaussian RP, R is Gaussian.

$$E[R] = E[X(3)] = 0$$

$$\sigma_R^2 = E[R^2] = E[X^2(3)] = E[X^2(t)] = R_x(0) = 1$$

$$\begin{aligned} P(X(3) > 2) &= P(R > 2) = 1 - P(R \leq 2) \\ &= 1 - \left(\frac{1}{2} + \frac{1}{2} \text{erf}\left(\frac{2}{\sqrt{1}}\right) \right) = \frac{1}{2} - \frac{1}{2} \text{erf}(2) \end{aligned}$$

(d)

$$S_x(f) = \mathcal{F}\{R_x(\tau)\}$$

$$= \mathcal{F}\{e^{-|\tau|/4}\}$$

$$= \int_{-\infty}^{\infty} e^{-|\tau|/4} e^{-j2\pi f\tau} d\tau$$

$$= \int_{-\infty}^0 e^{\tau/4} e^{-j2\pi f\tau} d\tau + \int_0^{\infty} e^{-\tau/4} e^{-j2\pi f\tau} d\tau$$

$$= \int_{-\infty}^0 e^{+(1/4 - j2\pi f)\tau} d\tau + \int_0^{\infty} e^{-(1/4 + j2\pi f)\tau} d\tau$$

$$= \frac{1}{1/4 - j2\pi f} e^{(1/4 - j2\pi f)\tau} \Big|_{-\infty}^0 + \frac{-1}{1/4 + j2\pi f} e^{-(1/4 + j2\pi f)\tau} \Big|_0^{\infty}$$

$$= \frac{1}{1/4 - j2\pi f} + \frac{1}{1/4 + j2\pi f}$$

$$= \frac{1/4 + j2\pi f + 1/4 - j2\pi f}{1/16 + 4\pi^2 f^2}$$

$$= \frac{8}{1 + 64\pi^2 f^2}$$

(e) $S_x(f) = \frac{8}{1 + 64\pi^2 f^2} = \frac{2\sqrt{2}}{1 - j8\pi f} \frac{2\sqrt{2}}{1 + j8\pi f}$

$$\Rightarrow H(f) = \frac{2\sqrt{2}}{1 - j8\pi f} \sqrt{\frac{2}{N_0}} = \frac{4}{\sqrt{N_0}(1 - j8\pi f)}$$

(f) $Z = X(0) + X(1) + X(2)$

Because $X(t)$ is a Gaussian RP, $X(0)$, $X(1)$, and $X(2)$ are jointly Gaussian $\Rightarrow Z$ is a linear combination of jointly Gaussian RVs $\Rightarrow Z$ is Gaussian

$$E[Z] = E[X(0)] + E[X(1)] + E[X(2)] = 0$$

$$\sigma_z^2 = E[Z^2] - (E[Z])^2 = E[Z^2] = E[(X(0) + X(1) + X(2))^2]$$

$$= E[X^2(0)] + E[X^2(1)] + E[X^2(2)] + 2E[X(0)X(1)]$$

$$+ 2E[X(1)X(2)] + 2E[X(0)X(2)]$$

$$= 3R_x(0) + 4R_x(1) + 2R_x(2)$$

$$= 3 + 4e^{-1/4} + 2e^{-1/2}$$

$$\Rightarrow f_2(z) = \frac{1}{\sqrt{2\pi(3+4e^{-1/4}+2e^{-1/2})}} e^{-z^2/2(3+4e^{-1/4}+2e^{-1/2})}$$

(g)

Let $T = X(0) + X(1)$. As in (f), T is Gaussian with $E[T] = 0$ and

$$\begin{aligned} \sigma_T^2 &= E[T^2] - (E[T])^2 = E[T^2] \\ &= E[X^2(0)] + E[X^2(1)] + 2E[X(0)X(1)] \\ &= 2R_X(0) + 2R_X(1) = 2 + 2e^{-1/4} \end{aligned}$$

$$\begin{aligned} P(T > 3) &= 1 - P(T \leq 3) \\ &= 1 - \left(\frac{1}{2} + \frac{1}{2} \operatorname{erf} \left(\frac{3}{\sqrt{2+2e^{-1/4}}} \right) \right) \\ &= \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left(\frac{3}{\sqrt{2+2e^{-1/4}}} \right) \end{aligned}$$

(h)

$$Y = \int_0^T N(t) dt$$

$$N(t) \rightarrow \boxed{h(\cdot)} \rightarrow m(t)$$

$$b(t) = \begin{cases} 1 & 0 \leq t \leq T \\ 0 & \text{else} \end{cases}$$

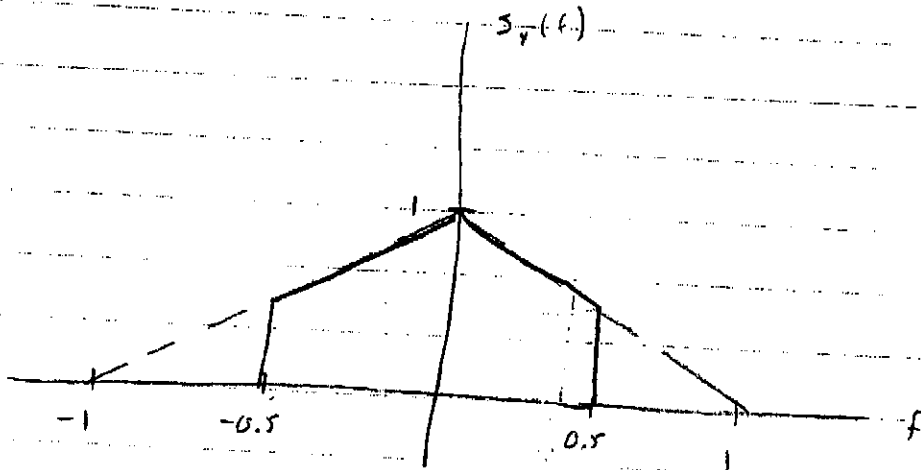
$m(t)$ is a Gaussian RP (since $N(t)$ is a Gaussian RP).

$\Rightarrow Y = m(T)$ is Gaussian

$$E[Y] = E\left[\int_0^T N(t) dt\right] = \int_0^T E[N(t)] dt = 0$$

IGNORE

2) (a) $S_Y(f) = |H(f)|^2 S_X(f)$



$$\Rightarrow S_Y(f) = \begin{cases} 1 - |f|, & |f| \leq 0.5 \\ 0, & \text{else} \end{cases}$$

$$P_Y = \int_{-\infty}^{\infty} S_Y(f) df = 0.5 + 2 \left(\frac{1}{2} \cdot 0.5 \cdot 0.5 \right) = 0.75$$

Because $X(t)$ is Gaussian, so is $Y(t)$

$\Rightarrow Y(0)$ is Gaussian

$$E\{Y(0)\} = 0 \quad \text{Var}\{Y(0)\} = E\{Y^2(0)\} - (E\{Y(0)\})^2$$

$$= E\{Y^2(0)\}$$

$$= R_Y(0) = P_Y = 0.75$$

$$P(Y(0) \geq 2) = 1 - P(Y < 2)$$

$$= 1 - \left(\frac{1}{2} + \frac{1}{2} \text{erf} \left(\frac{2}{\sqrt{2} \sqrt{3/4}} \right) \right)$$

$$= \frac{1}{2} - \frac{1}{2} \text{erf} \left(\frac{2\sqrt{2}}{\sqrt{3}} \right)$$

$$(b) \quad H(f) = j2\pi f$$

$$\Rightarrow H(f)H^*(f) = j2\pi f(-j2\pi f) = 4\pi^2 f^2$$

$$\Rightarrow S_y(f) = S_x(f) |H(f)|^2 = \begin{cases} (1-f) 4\pi^2 f^2 & |f| \leq 1 \\ 0 & \text{else} \end{cases}$$

$$P_y = \int_{-\infty}^{\infty} S_y(f) df$$

$$= 2 \int_0^1 (1-f) 4\pi^2 f^2 df$$

$$= 8\pi^2 \int_0^1 (f^2 - f^3) df$$

$$= 8\pi^2 \left(\frac{1}{3} - \frac{1}{4} \right)$$

$$= \frac{2}{3} \pi^2$$

$$P[Y(0) \geq 2] = 1 - P[Y(0) < 2]$$

$$= 1 - \left(\frac{1}{2} + \frac{1}{2} \operatorname{erf} \left(\frac{\sqrt{2}}{\sqrt{2/3} \pi^2} \right) \right)$$

$$= \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left(\frac{\sqrt{2}}{\sqrt{2/3} \pi^2} \right)$$

$$= \frac{1}{2} - \frac{1}{2} \operatorname{erf} \left(\frac{1}{\sqrt{\pi^2/3}} \right)$$

3) $S_x(f) = 10$

(a) $S_y(f) = \begin{cases} 10, & |f| < 3 \\ 0, & \text{else} \end{cases}$

$\Rightarrow P_y = \int_{-\infty}^{\infty} S_y(f) df = 60$

(b)

$S_z(f) = \begin{cases} 10 e^{-4f^2}, & |f| < 3 \\ 0, & \text{else} \end{cases}$

$P_z = \int_{-3}^3 10 e^{-4f^2} df$

$= \int_{-3}^3 10 e^{-f^2/2 \cdot (1/8)} df$

$= 10 \cdot \sqrt{2\pi(1/8)} \int_{-3}^3 \frac{1}{\sqrt{2\pi(1/8)}} e^{-f^2/2 \cdot (1/8)} df$

$= 5\sqrt{\pi} (P(z \leq 3) - P(z \leq -3)) \quad \text{where } z \sim N(0, 1/8)$

$= 5\sqrt{\pi} \left(\frac{1}{2} + \frac{1}{2} \operatorname{erf}(6) \right) - \left(\frac{1}{2} - \frac{1}{2} \operatorname{erf}(6) \right) \frac{\sigma - \mu}{\sqrt{2\sigma}} = \frac{3}{\sqrt{2}} \cdot \frac{1}{2\sqrt{2}} = 6$

$= 5\sqrt{\pi} \operatorname{erf}(6)$

4) (a)

$$P_x = R_x(0) = 20$$

(b)

$$\begin{aligned} m_Y(t) &= E[4 \cos(2\pi 30t) + X(t)] \\ &= 4 \cos(2\pi 30t) + \cancel{E[X(t)]} \rightarrow 0 \\ &= 4 \cos(2\pi 30t) \end{aligned}$$

$$\begin{aligned} R_Y(t_1, t_2) &= E[Y(t_1)Y(t_2)] \\ &= E[(4 \cos(2\pi 30t_1) + X(t_1)) \\ &\quad (4 \cos(2\pi 30t_2) + X(t_2))] \\ &= 16 \cos(2\pi 30t_1) \cos(2\pi 30t_2) \\ &\quad + 4 \cos(2\pi 30t_1) \cancel{E[X(t_1)]} \rightarrow 0 \\ &\quad + 4 \cos(2\pi 30t_2) \cancel{E[X(t_2)]} \rightarrow 0 \\ &\quad + E[X(t_1)X(t_2)] \\ &= 16 \cos(2\pi 30t_1) \cos(2\pi 30t_2) + 20 \operatorname{sinc}^2(80(t_2 - t_1)) \end{aligned}$$

$m_Y(t)$ not constant, not WSS

(c)

Yes

Consider any $Y(t_1), Y(t_2), \dots, Y(t_N)$

$$Z = \sum_{i=1}^N a_i Y(t_i) = 4 \underbrace{\sum_{i=1}^N a_i \cos(2\pi t_i)}_{\text{constant}} + \sum_{i=1}^N a_i X(t_i)$$

$\Rightarrow Z$ is Gaussian Gaussian - since $X(t_1), X(t_2), \dots, X(t_N)$ jointly Gaussian

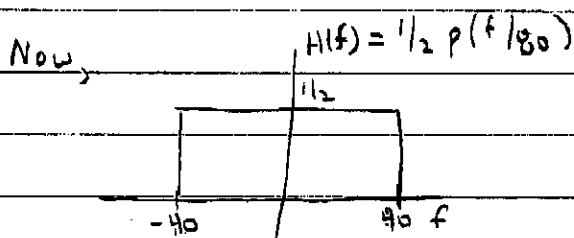
\Rightarrow by Cramer-Wald Device, $Y(t_1), Y(t_2), \dots, Y(t_N)$ are jointly Gaussian $\Rightarrow Y(t)$ is a Gaussian RP

(d)

$$z(t) = h(t) * y(t)$$

$$= h(t) * (4 \cos(2\pi 30t) + x(t))$$

$$= h(t) * 4 \cos(2\pi 30t) + h(t) * x(t)$$



$$\Rightarrow z(t) = 2 \cos(2\pi 30t) + u(t) \quad u(t) \stackrel{\Delta}{=} h(t) * x(t)$$

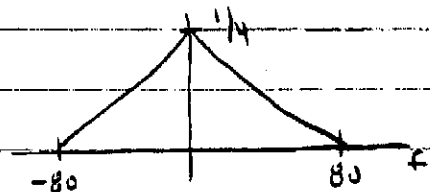
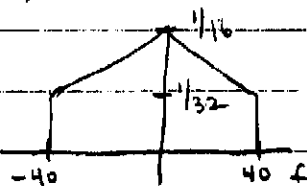
$$P_z = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T E \left[(2 \cos(2\pi 30t) + u(t))^2 \right] dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T (4 \cos^2(2\pi 30t) + 4 \cos(2\pi 30t) \cancel{E[u(t)]} + E[u^2(t)]) dt$$

$$= \lim_{T \rightarrow \infty} \frac{4}{2T} \int_{-T}^T (\frac{1}{2} + \frac{1}{2} \cos(2\pi 60t)) dt + E[u^2(t)]$$

$$= 2 + E[u^2(t)]$$

Now, $S_u(f) = |H(f)|^2 S_x(f)$ where $S_x(f) = \frac{1}{4} \Lambda(f/80)$



$$P_u = \int_{-\infty}^{\infty} S_u(f) df = 80 \cdot \frac{1}{32} + 80 \cdot \frac{1}{32} \cdot \frac{1}{2}$$

$$= \frac{5}{2} + \frac{5}{4} = \frac{15}{4}$$

$$\Rightarrow P_z = \frac{23}{4}$$