

Exam 1 Solutions

- 1 -

ECE 313

Fall, 2012

1) (a)

$$x(t) = 5 \Lambda\left(\frac{t-2}{2}\right) - 5 \Lambda\left(\frac{t+2}{2}\right)$$

(b) $X(f) = 5 \cdot 2 \operatorname{sinc}^2(2f) e^{-j2\pi f 2}$ scaling/shifting
 $- 5 \cdot 2 \operatorname{sinc}^2(2f) e^{j2\pi f 2}$
 $= 10 \operatorname{sinc}^2(2f) \cdot (e^{-j2\pi f 2} - e^{j2\pi f 2})$

(c) $X(f) = 10 \operatorname{sinc}^2(2f) \cdot 2j \left(\frac{1}{2j} e^{-j2\pi f 2} - \frac{1}{2j} e^{j2\pi f 2} \right)$
 $= 20j \operatorname{sinc}^2(2f) (-\sin(2\pi 2f))$

$$= -20j \operatorname{sinc}^2(2f) \cos(2\pi 2f + \pi/2)$$

$$a = -20j, b = 2, c = 2, \theta = -\pi/2$$

(lots of other correct answers) also: $\theta = 3\pi/2$
-or- you could use $a = 20j$, and $\theta = \pi/2$ or $\theta = -3\pi/2$, etc.)

2) (a) no. If the response to $u(t)$ is $\Lambda(t-1)$, the response of a linear system to $2u(t)$ is $2\Lambda(t-1)$.

(b) might be. The responses to $u(t)$, $u(t-1)$ agree with the TI definition. But TI requires it to be true for all inputs, all shifts.

3)

(a) yes

$$x_1(t) \rightarrow \boxed{} \rightarrow y_1(t) = \int_0^t x_1(\tau) d\tau$$

$$x_2(t) \rightarrow \boxed{} \rightarrow y_2(t) = \int_0^t x_2(\tau) d\tau$$

$$\begin{aligned} \alpha_1 x_1(t) + \alpha_2 x_2(t) &\rightarrow \boxed{} \rightarrow \int_0^t (\alpha_1 x_1(\tau) + \alpha_2 x_2(\tau)) d\tau \\ &= \alpha_1 \int_0^t x_1(\tau) d\tau + \alpha_2 \int_0^t x_2(\tau) d\tau \\ &= \alpha_1 y_1(t) + \alpha_2 y_2(t) \end{aligned}$$

(b) noCounterexample

$$x_1(t) = \delta(t+1) \Rightarrow y_1(t) = 0$$

$$x_2(t) = \delta(t-1) \Rightarrow y_2(t) = u(t-1) \neq y_1(t-2)$$

(many other possibilities of course)

$$(c) \quad y(t) = \int_0^t 3\delta(\tau-2) d\tau = 3 \int_0^t \delta(\tau-2) d\tau$$

$$= \begin{cases} 1, & \text{if } 2 \in [0, t] \\ 0, & \text{else} \end{cases} = \begin{cases} 1, & t \in [2, \infty) \\ 0, & \text{else} \end{cases}$$

$$\Rightarrow y(t) = u(t-2)$$

4)

(a)

$$X_1(t) = \frac{5}{2} \delta(t-2.5) + \frac{5}{2} \delta(t+2.5)$$

$$Y_1(f) = H(f)X_1(f) = \frac{15}{4} \delta(f-2.5) + \frac{15}{4} \delta(f+2.5)$$

$$\Rightarrow y_1(t) = \frac{15}{2} \cos(2\pi \cdot 2.5 t)$$

(b)

$$P = \frac{A^2}{2} = \frac{225}{4} \cdot \frac{1}{2} = \frac{225}{8}$$

(c)

$$X_2(t) = \frac{5}{2j} \delta(t-2.5) - \frac{5}{2j} \delta(t+2.5) + 5 \delta(t-10) + 5 \delta(t+10)$$

$$Y_2(f) = H(f)X_2(f) = \frac{5}{2j} \cdot \frac{3}{2} \cdot e^{-j\pi \cdot 1/2} \delta(f-2.5)$$

$$- \frac{5}{2j} \cdot \frac{3}{2} \cdot e^{j\pi \cdot 1/2} \delta(f+2.5)$$

$$= -\frac{15}{4} \delta(f-2.5) - \frac{15}{4} \delta(f+2.5)$$

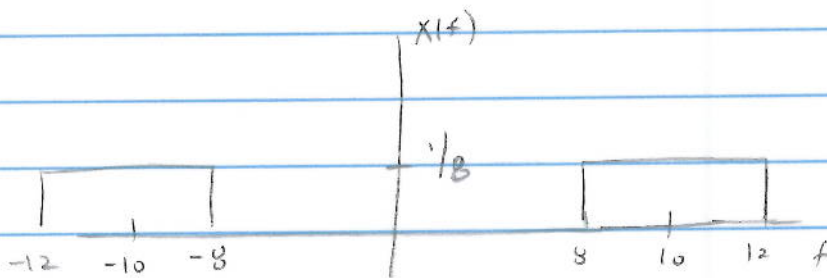
$$= -\frac{15}{2} \cos(2\pi \cdot 2.5 t)$$

5)

(a)

$$x(t) = \text{sinc}(4t) \cos(2\pi 10t)$$

$$\begin{aligned} \Rightarrow X(f) &= \mathcal{F}\{\text{sinc}(4t)\} * \mathcal{F}\{\cos(2\pi 10t)\} \\ &= \frac{1}{4} \text{rect}(f/4) * \left(\frac{1}{2} \delta(f-10) + \frac{1}{2} \delta(f+10) \right) \\ &= \frac{1}{8} \text{rect}\left(\frac{f-10}{4}\right) + \frac{1}{8} \text{rect}\left(\frac{f+10}{4}\right) \end{aligned}$$



(b)

$$E_x = \int_{-\infty}^{\infty} x^2(t) dt = \int_{-\infty}^{\infty} |X(f)|^2 df$$

$$= 2 \cdot \int_8^{12} \frac{1}{64} df$$

$$= 2 \cdot \frac{4}{64} = \frac{1}{8}$$

remember to square 1/8

(c) IF LTI, I can find an $H(f)$.

Try $H(f) = Y(f)/X(f) \Rightarrow$ divide by zero at $f \in [8, 12]$

No.

$$y(t) = x(t) \cos(2\pi 10t)$$

$$= \text{sinc}(4t) \cos^2(2\pi 10t)$$

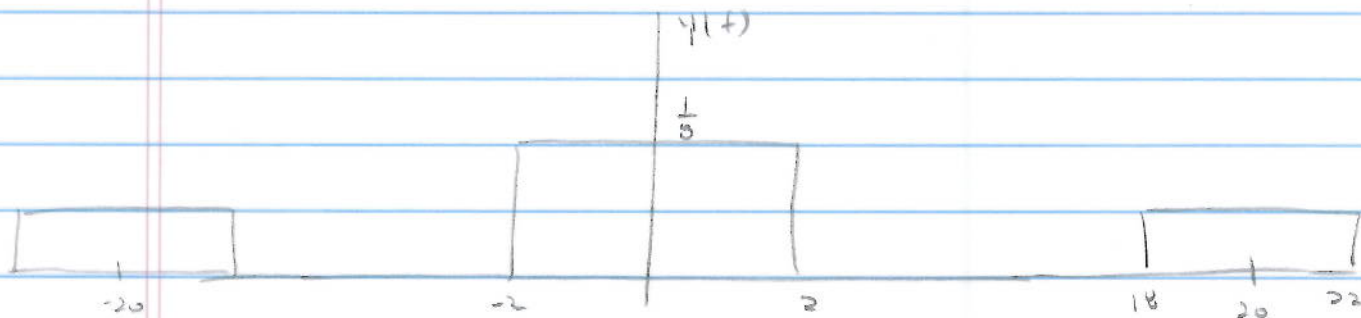
$$= \text{sinc}(4t) \cdot \left(\frac{1}{2} + \frac{1}{2} \cos(2\pi 20t) \right)$$

$$= \frac{1}{2} \text{sinc}(4t) + \frac{1}{2} \text{sinc}(4t) \cos(2\pi 20t)$$

$$= \frac{1}{8} p\left(\frac{f}{4}\right) + \frac{1}{80} p\left(\frac{f-20}{4}\right) + \frac{1}{16} p\left(\frac{f+20}{4}\right)$$

can also do

$$Y(f) = X(f) * \left(\frac{1}{2} \delta(f-f_0) + \frac{1}{2} \delta(f+f_0) \right)$$



$$\text{Let } H(f) = \begin{cases} 1, & |f| \leq 2 \\ 0, & \text{else} \end{cases}$$

Then

$$H(f) Y(f) = \frac{1}{8} p\left(\frac{f}{4}\right)$$

and the output is

$$\mathcal{F}^{-1} \left\{ \frac{1}{8} p\left(\frac{f}{4}\right) \right\} = 2 \text{sinc}(4t) = 2 \text{rect}(t)$$